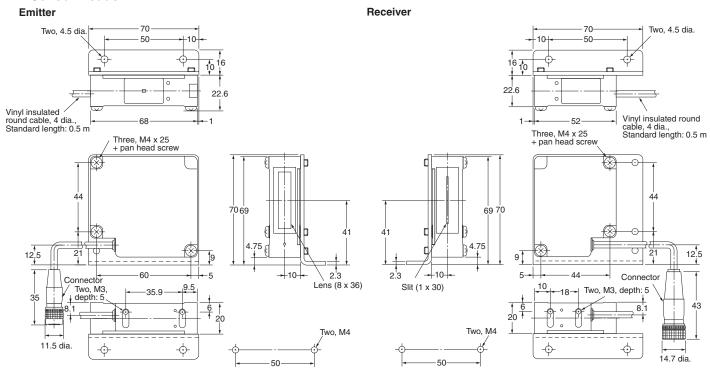
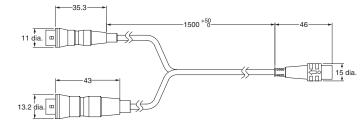
Dimensions (Unit: mm)

■ Sensor Heads



■ Sensor Head - Amplifier Connection Cable



This document provides information mainly for selecting suitable models.

Please read the Instruction Sheet carefully for information that the user must understand and

accept before purchase, including information on warranty, limitations of liability, and

Note: Do not use this document to operate the Unit.

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Beijing, 100031 China
Tel: (86)10-8391-3005/Fax: (86)10-8391-3688
Note: Specifications subject to change without notice.

Cat. No. E362-E1-01

Authorized Distributor:



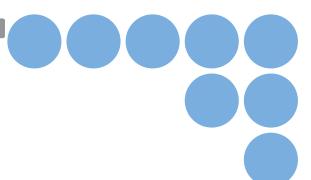
Authorised Distributors:-

ASH & ALAIN INDIA PVT LTD S-100, F.I.E.E., Okhla Industrial Area, Phase-ii, New Delhi-110020(India)



OMRON

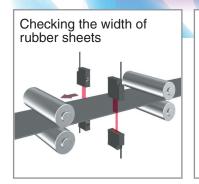
Smart Sensors Through-beam Laser Type **ZX-LT030**

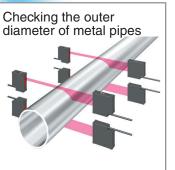


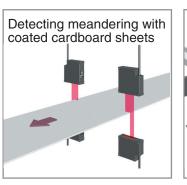
New Line-up of Wide-line-beam Sensors (30-mm Width)!

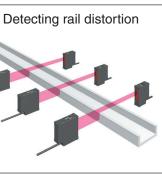


ZX Series multi-point measurement and calculation functions further expand the application coverage.









ZX-LT030

■ Features

Multi-Point Measurement with Calculation Functions

Use of the ZX-CAL2 Calculating Unit makes it easy to configure inspection systems requiring outer diameter (A-B) or width (A+B) calculations.



The ZX-SAM14 Multi-point Smart Sensor Package lets you easily perform multi-point calculations on a personal computer.



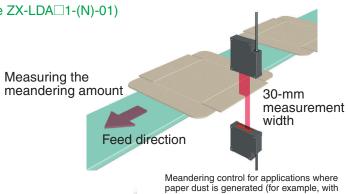
Multi-point Smart Sensor Package

Note: The ZX-CN1 Calculating Unit is

used for multi-point calculat

● Remote (External) Reference Light Intensity Setting (Use ZX-LDA□1-(N)-01)

The reference light intensity can be set to cancel measurement errors due to the effects of paper dust and other matter when there is no sensing object present. This enables high-speed meandering control.



"Front" APC Function

Front APC (Auto Power Control) reduces the effect of light reflecting from wafers. Ideal for high-precision, high-speed orientation flat positioning.

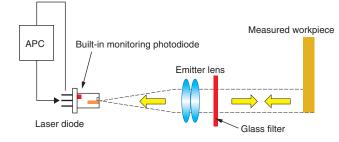


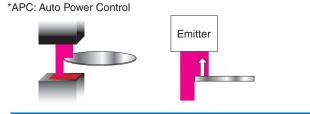
Technology Front APC nulls the effects of light reflections from workpieces with mirror surfaces

The output power of the semiconductor laser in conventional laser sensors has to be monitored and controlled. When reflections from the workpiece enter the built-in monitoring photodiode that is used for this purpose, the output power changes and adversely affects the measurement. The ZX-LT030 uses front APC technology to solve this problem.

Integrated APC Method (Conventional Laser Sensor)

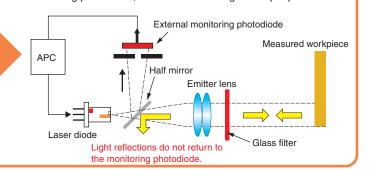
Light reflected from the workpiece returns directly to the monitoring photodiode inside the laser diode, which reduces the output power and causes measurement errors.





Front APC Method (ZX-LT030)

Light reflected from the workpiece does not return to the external monitoring photodiode, so there is no change in output power.



Ordering Information

(Unit: mm)

■ Sensor Heads (Through-beam)

Optical system	Measuring width	Sensing distance	Resolution (See note.)	Model
Through-beam	1 mm dia.	0 to 2000 mm		ZX-LT001
	5 mm		4 μm	ZX-LT005
	10 mm	0 to 500 mm		ZX-LT010
	30 mm		12 μm	ZX-LT030

Note: For an average count of 64.

■ Amplifier Units

Appearance	Power supply	Output type	Model	
	DC -	NPN	ZX-LDA11-N	
333		PNP	ZX-LDA41-N	

Note: Compatible connection with the Sensor Head.

Ratings

Model Item		ZX-LT001		ZX-LT005	ZX-LT010	ZX-LT030
Applicable Amplifier Units						
Light source						
٨	Maximum output	0.2 mW max.		0.35 mW	0.2 mW max.	
Measurement distance		0 to 500 mm	500 to 2000 mm	0 to 500 mm		
Measurement width		1-mm dia.	1- to 2.5-mm dia.	5 mm	10 mm	30 mm
Min	nimum sensing object	8-μm dia. (opaque)	50-μm dia. (opaque)	0.05-mm dia. (opaque)	0.1-mm dia. (opaque)	0.3-mm dia. (opaque)
Resolution (See note 1.)		4 μm (See note 2.)		4 μm (See note 3.)		12 μm (See note 4.)
Temperature characteristic			±0.3% FS/°C			
Ambient illumination						
Ambient temperature						
Ambient humidity						
als	Case		Zina dia saat			
Materials	Cover		Zinc die-cast			
Ma	Front filter					
Degree of protection						
Weight (packed state)			Approx. 450 g			
Accessories		Instruction manual, se				
		Optical axis adjustme	Mounting Bracket			

- Note 1. This value is obtained by converting the deviation (±3σ) in the linear output that results when the sensor head is connected to the amplifier unit, into the measurement width.
 - 2. For an average count of 64 with measurement distance of 0 to 500 mm. The value is 5 μm for an average count of 32. This is the value that results when a minimum sensing object blocks the light near the center of the 1-mm measurement width.
 - 3. For an average count of 64. The value is 5 μm for an average count of 32.
 - 4. For an average count of 64. The value is 15 μm for an average count of 32.

Engineering Data

Linearity Characteristic (WD: Distance from Receiver to workpiece)

Light interruption (mm)